1 The matrix that will reflect the plane in the y-axis is given by

$$\begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}.$$

The matrix that will dilate the result by a factor of ${\bf 3}$ from the ${\it x}$ -axis is given by

$$\begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix}$$

Therefore, the matrix of the composition transformation is

$$\begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & 3 \end{bmatrix}.$$

2 The matrix that will rotate the plane by 90° anticlockwise is given by

$$\begin{bmatrix} \cos 90^\circ & -\sin 90^\circ \\ \sin 90^\circ & \cos 90^\circ \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}.$$

The matrix that will reflect the result in the x-axis is given by

$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}.$$

Therefore, the matrix of the composition transformation is

$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}.$$

3 a The matrix that will reflect the plane in the x-axis is given by

$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}.$$

The matrix that will reflect the plane in the y-axis is given by

$$\begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}.$$

Therefore, the matrix of the composition transformation is

$$\begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}.$$

 ${f b}$ The matrix that will rotate the plane by 180° clockwise is given by

$$\begin{bmatrix} \cos 180^\circ & -\sin 180^\circ \\ \sin 180^\circ & \cos 180^\circ \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix},$$

which is the same as the matrix found above.

4 a T_1 : The matrix that will reflect the plane in the x-axis is given by

$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}.$$

 T_2 : The matrix that will dilate the result by a factor of ${f 2}$ from the y-axis is given by

$$\begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}.$$

Therefore, the matrix of \mathcal{T}_1 followed by \mathcal{T}_2 will be

$$\begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix}.$$

$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix}.$$

- c No. The order of transformation does not matter in this instance, since the two matrices are the same.
- **5 a** T_1 : The matrix that will rotate the plane by 90° clockwise is given by

$$\begin{bmatrix} \cos(-90^\circ) & -\sin(-90^\circ) \\ \sin(-90^\circ) & \cos(-90^\circ) \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}.$$

 T_2 : The matrix that will reflect the plane in the line y=x is given by

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}.$$

Therefore, the matrix of T_1 followed by T_2 will be

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}.$$

b The matrix of T_2 followed by T_1 will be

$$\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}.$$

- **c** Yes. The order of transformation does matter in this instance, as the two matrices are different (the first gives the reflection in the *y*-axis, the second a reflection in the *x*-axis).
- 6 a

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} -3 \\ 5 \end{bmatrix}$$
$$= \begin{bmatrix} -x \\ y \end{bmatrix} + \begin{bmatrix} -3 \\ 5 \end{bmatrix}$$
$$= \begin{bmatrix} -x - 3 \\ y + 5 \end{bmatrix}$$

Therefore, the transformation is (x,y) o (-x-3,y+5).

 $\mathbf{b} \quad \begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{pmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} -3 \\ 5 \end{bmatrix} \end{pmatrix}$ $= \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x - 3 \\ y + 5 \end{bmatrix}$ $= \begin{bmatrix} -x + 3 \\ y + 5 \end{bmatrix}$

Therefore, the transformation is $(x, y) \rightarrow (-x + 3, y + 5)$.

- **c** Yes. The order of transformation does matter in this instance, as the rule for each composition is different.
- **7 a** This is a reflection in the x-axis followed by a dilation from the y-axis by a factor of 2 (or visa versa):

$$\begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix}.$$

b This is a reflection in the x-axis followed by a dilation from the x-axis by a factor of 3 (or visa versa):

$$\begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & -3 \end{bmatrix}.$$

c This is a reflection in the line y = x followed by a dilation from the x-axis by a factor of 2:

$$\begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 2 & 0 \end{bmatrix}.$$

Alternatively, it is a dilation from the y-axis by a factor of 2 followed by a reflection in the line y = x:

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 2 & 0 \end{bmatrix}.$$

This is a reflection in the line y = -x followed by a dilation from the y-axis by a factor of 2:

$$\begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & -2 \\ -1 & 0 \end{bmatrix}.$$

Alternatively, it is a dilation from the x-axis by a factor of 2 followed by a reflection in the line y = -x:

$$\begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} 0 & -2 \\ -1 & 0 \end{bmatrix}.$$

The required matrix is
$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}.$$

The above matrix corresponds to a rotation by angle $\theta=90^\circ$ since

$$\begin{bmatrix} \cos 90^\circ & -\sin 90^\circ \\ \sin 90^\circ & \cos 90^\circ \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}.$$

We require that:

require that:
$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

$$\begin{bmatrix} -\sin \theta & -\cos \theta \\ \cos \theta & \sin \theta \end{bmatrix} = \begin{bmatrix} \sin \theta & \cos \theta \\ \cos \theta & -\sin \theta \end{bmatrix}$$

For these two matrices to be equal, we required that

$$-\sin \theta = \sin \theta$$

 $2\sin \theta = 0$
 $\sin \theta = 0$

$$\theta = 180^{\circ} k$$
, where $k \in \mathbb{Z}$.

Matrix A^2 will rotate the plane by angle 2θ . 10a

b

$$A^2 = egin{bmatrix} \cos heta & -\sin heta \ \sin heta & \cos heta \end{bmatrix} egin{bmatrix} \cos heta & -\sin heta \ \sin heta & \cos heta \end{bmatrix} \ = egin{bmatrix} \cos^2 heta - \sin^2 heta & -2\sin heta \cos heta \ 2\sin heta \cos heta & \cos^2 heta - \sin^2 heta \end{bmatrix}$$

Since A^2 will rotate the plane by angle 2θ , another expression for A^2 is

$$A^2 = egin{bmatrix} \cos 2 heta & -\sin 2 heta \ \sin 2 heta & \cos 2 heta \end{bmatrix}.$$

Equating the two expressions for
$$A^2$$
 gives
$$\begin{bmatrix} \cos 2\theta & -\sin 2\theta \\ \sin 2\theta & \cos 2\theta \end{bmatrix} = \begin{bmatrix} \cos^2\theta - \sin^2\theta & -2\sin\theta\cos\theta \\ 2\sin\theta\cos\theta & \cos^2\theta - \sin^2\theta \end{bmatrix}.$$

Therefore,

$$\cos 2\theta = \cos^2 \theta - \sin^2 \theta$$

$$\sin 2\theta = 2\sin\theta\cos\theta.$$

11a

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} y \\ x \end{bmatrix} + \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$=\begin{bmatrix} y+1 \\ x+2 \end{bmatrix}$$

Therefore, the rule can be written in the form (x,y) o (y+1,x+2) or in the form x'=y+1 y'=x+2.

We have,

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} y+1 \\ x+2 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x+2 \\ y+1 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \left(\begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} 2 \\ 1 \end{bmatrix} \right)$$

This shows the transformation can be expressed as a reflection in the line y=x followed by a translation in the direction of vector $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$.

$$\begin{bmatrix} \cos(60) & -\sin(60) \\ \sin(60) & \cos(60) \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & \frac{1}{2} \end{bmatrix}$$

$$\begin{aligned} \textbf{b} & \begin{bmatrix} \cos(-45^\circ) & -\sin(-45^\circ) \\ \sin(-45^\circ) & \cos(-45^\circ) \end{bmatrix} \\ = & \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \\ = & \begin{bmatrix} \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \\ -\frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{bmatrix} \end{aligned}$$

A 60° rotation followed by a -45° rotation will give a 15° rotation. Therefore, the required matrix is.

$$\begin{bmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \\ -\frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{bmatrix}$$

$$= \begin{bmatrix} \frac{\sqrt{2} + \sqrt{6}}{4} & \frac{\sqrt{2} - \sqrt{6}}{4} \\ \frac{\sqrt{6} - \sqrt{2}}{4} & \frac{\sqrt{6} + \sqrt{2}}{2} \end{bmatrix}$$

The rotation matrix of 15° is also given by the expression

$$\begin{bmatrix} \cos(15) & -\sin(15) \\ \sin(15) & \cos(15) \end{bmatrix}.$$

Comparing the entries of these two matrices gives d

$$\cos 15^\circ = rac{\sqrt{2}+\sqrt{6}}{4},$$

$$\sin 15^\circ = \frac{\sqrt{6} - \sqrt{2}}{4},$$

13 The matrix that will reflect the plane in the line $y = x \tan \phi$ is

$$\begin{bmatrix} \cos 2\phi & \sin 2\phi \\ \sin 2\phi & -\cos 2\phi \end{bmatrix}.$$

The matrix that will reflect the plane in the line $y = x \tan \theta$ is

$$\begin{bmatrix} \cos 2\theta & \sin 2\theta \\ \sin 2\theta & -\cos 2\theta \end{bmatrix}$$

Therefore, the matrix of the composition transformation is

$$\begin{bmatrix} \cos 2\theta & \sin 2\theta \\ \sin 2\theta & -\cos 2\theta \end{bmatrix} \begin{bmatrix} \cos 2\phi & \sin 2\phi \\ \sin 2\phi & -\cos 2\phi \end{bmatrix}$$

$$= \begin{bmatrix} \cos 2\theta \cos 2\phi + \sin 2\theta \sin 2\phi & \cos 2\theta \sin 2\phi - \sin 2\theta \cos 2\phi \\ \sin 2\theta \cos 2\phi - \cos 2\theta \sin 2\phi & \cos 2\theta \cos 2\phi + \sin 2\theta \sin 2\phi \end{bmatrix}$$

$$= \begin{bmatrix} \cos 2\theta \cos 2\phi + \sin 2\theta \sin 2\phi & -(\cos 2\theta \sin 2\phi - \cos 2\theta \sin 2\phi) \\ \cos 2\theta \sin 2\phi - \cos 2\theta \sin 2\phi & \cos 2\theta \cos 2\phi + \sin 2\theta \sin 2\phi \end{bmatrix}$$

$$= \begin{bmatrix} \cos(2\theta - 2\phi) & -\sin(2\theta - 2\phi) \\ \sin(2\theta - 2\phi) & \cos(2\theta - 2\phi) \end{bmatrix}$$

This is a rotation matrix corresponding to angle $2\theta-2\phi$.